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⊕ Back to my courses

RC Excavator - How To

69% COMPLETE

What We're Building \sim

Sourcing Parts ∨

Soldering ✓

Uploading Code to ESP32

3D Printing ∨

Assembling Lower Body & Track Support

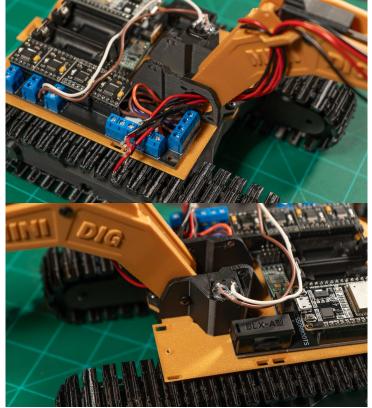
Securing Arm to Chassis

Parts Required

- 3x 2.6x6mm Screws
- 1x 3D Printed Rotator Cuff

STEPS

1.) With the wires routed through to the bottom of the main boom insert it into the main boom holder and gently pass all the wires through the right side if looking from the back. Secure the left side with a 2x6mm screw.



2.) Route all the wires through the 3D

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Arm Assembly

- ^
- Motor Holders and Push Rods
- ⊘ Boom & Dipper
 Assembly
- Bucket Assembly

Securing Arm to Chassis

- ✓ Main Boom N20 motor
- **⊘** Routing Wires

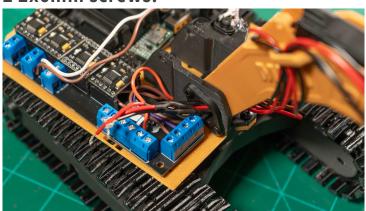
Cab Lights and Rear

Cover

Test Drive

Attachments/Upgrades ∨

Printed rotator cuff and press it into place so that it passes through the main boom holder and inserts into the main boom. Secure the rotator cuff via 2 2x6mm screws.



COMPLETE AND CONTINUE

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